

# HIMatrix

## Safety-Related Controller

### F20 01 Manual



HIMA Paul Hildebrandt GmbH + Co KG  
Industrial Automation

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## 1 Introduction

This manual describes the technical characteristics of the device and its use. It provides information on how to install, start up and configure the module.

### 1.1 Structure and Use of this Manual

The content of this manual is part of the hardware description of the HIMatrix programmable electronic system.

This manual is organized in the following main chapters:

- Introduction
- Safety
- Product Description
- Start-up
- Operation
- Maintenance
- Decommissioning
- Transport
- Disposal

HIMatrix controllers are available for the programming tools SILworX and ELOP II Factory. Which programming tool can be used, depends on the processor operating system of the HIMatrix controller, refer to the following table:

Programming tool	Processor operating system	Communication operating system
SILworX	CPU OS V7 and higher	COM OS V12 and higher
ELOP II Factory	CPU OS up to V6.x	COM OS up to V11.x

Table 1: Programming Tools for HIMatrix Controllers

In the manual, the differences are specified by using:

- Separated chapters
- Tables differentiating among the versions



**Projects created with ELOP II Factory cannot be edited with SILworX, and vice versa!**

---



Compact controllers and remote I/Os are referred to as *devices*.

---

Additionally, the following documents must be taken into account:

Name	Content	Document number
HIMatrix System Manual Compact Systems	Hardware description of the HIMatrix compact systems	HI 800 141 E
HIMatrix System Manual Modular System F60	Hardware description of the HIMatrix modular system	HI 800 191 E
HIMatrix Safety Manual	Safety functions of the HIMatrix system	HI 800 023 E
HIMatrix Safety Manual for Railway Applications	Safety functions of the HIMatrix system using the HIMatrix in railway applications	HI 800 437 E
SILworX Communication Manual	Description of the communication protocols, ComUserTask and their configuration in SILworX	HI 801 101 E
HIMatrix PROFIBUS DP Master/Slave Manual	Description of the PROFIBUS protocol and its configuration in ELOP II Factory	HI 800 009 E
HIMatrix Modbus Master/Slave Manual	Description of the Modbus protocol and its configuration in ELOP II Factory	HI 800 003 E
HIMatrix TCP S/R Manual	Description of the TCP S/R protocol and its configuration in ELOP II Factory	HI 800 117 E
HIMatrix ComUserTask (CUT) Manual	Description of the ComUserTask and its configuration in ELOP II Factory	HI 800 329 E
SILworX Online Help	Instructions on how to use SILworX	-
ELOP II Factory Online Help	Instructions on how to use ELOP II Factory, Ethernet IP protocol	-
SILworX First Steps	Introduction to SILworX using the HIMax system as an example	HI 801 103 E
ELOP II Factory First Steps	Introduction to ELOP II Factory	HI 800 006 E

Table 2: Additional Relevant Documents

The latest manuals can be downloaded from the HIMA website at [www.hima.com](http://www.hima.com). The revision index on the footer can be used to compare the current version of existing manuals with the Internet edition.

## 1.2

### Target Audience

This document addresses system planners, configuration engineers, programmers of automation devices and personnel authorized to implement, operate and maintain the modules and systems. Specialized knowledge of safety-related automation systems is required.

## 1.3 Formatting Conventions

To ensure improved readability and comprehensibility, the following fonts are used in this document:

<b>Bold</b>	To highlight important parts. Names of buttons, menu functions and tabs that can be clicked and used in the programming tool.
<i>Italics</i>	For parameters and system variables
Courier	Literal user inputs
RUN	Operating state are designated by capitals
Chapter 1.2.3	Cross references are hyperlinks even though they are not particularly marked. When the cursor hovers over a hyperlink, it changes its shape. Click the hyperlink to jump to the corresponding position.

Safety notes and operating tips are particularly marked.

### 1.3.1 Safety Notes

The safety notes are represented as described below.

These notes must absolutely be observed to reduce the risk to a minimum. The content is structured as follows:

- Signal word: warning, caution, notice
- Type and source of risk
- Consequences arising from non-observance
- Risk prevention

#### **⚠ SIGNAL WORD**



Type and source of risk!

Consequences arising from non-observance

Risk prevention

---

The signal words have the following meanings:

- Warning indicates hazardous situation which, if not avoided, could result in death or serious injury.
- Caution indicates hazardous situation which, if not avoided, could result in minor or modest injury.
- Notice indicates a hazardous situation which, if not avoided, could result in property damage.

#### **NOTE**



Type and source of damage!

Damage prevention

### 1.3.2 Operating Tips

Additional information is structured as presented in the following example:



The text corresponding to the additional information is located here.

---

Useful tips and tricks appear as follows:



The tip text is located here.

---

## 2 Safety

All safety information, notes and instructions specified in this document must be strictly observed. The product may only be used if all guidelines and safety instructions are adhered to.

This product is operated with SELV or PELV. No imminent risk results from the product itself. The use in Ex-Zone is permitted if additional measures are taken.

### 2.1 Intended Use

HIMatrix components are designed for assembling safety-related controller systems.

When using the components in the HIMatrix system, comply with the following general requirements.

#### 2.1.1 Environmental Requirements

Requirement type	Range of values <sup>1)</sup>
Protection class	Protection class III in accordance with IEC/EN 61131-2
Ambient temperature	0...+60 °C
Storage temperature	-40...+85 °C
Pollution	Pollution degree II in accordance with IEC/EN 61131-2
Altitude	< 2000 m
Housing	Standard: IP20
Supply voltage	24 VDC

<sup>1)</sup> The values specified in the technical data apply and are decisive for devices with extended environmental requirements.

Table 3: Environmental Requirements

Exposing the HIMatrix system to environmental conditions other than those specified in this manual can cause the HIMatrix system to malfunction.

#### 2.1.2 ESD Protective Measures

Only personnel with knowledge of ESD protective measures may modify or extend the system or replace devices.

#### NOTE

##### Device damage due to electrostatic discharge!

- When performing the work, make sure that the workspace is free of static, and wear an ESD wrist strap.
- If not used, ensure that the device is protected from electrostatic discharge, e.g., by storing it in its packaging.



## 2.2 Residual Risk

No imminent risk results from a HIMatrix system itself.

Residual risk may result from:

- Faults related to engineering
- Faults related to the user program
- Faults related to the wiring

## 2.3 Safety Precautions

Observe all local safety requirements and use the protective equipment required on site.

## 2.4 Emergency Information

A HIMatrix system is a part of the safety equipment of a site. If a device or a module fails, the system enters the safe state.

In case of emergency, no action that may prevent the HIMatrix systems from operating safely is permitted.

### 3 Product Description

The safety-related **F20** controller is a compact system in a metal housing with 8 digital input and output (DIO) channels that can be configured as digital inputs or digital outputs. Additionally, 4 pulsed outputs are available. For external communication, 2 Ethernet connections and 2 fieldbus interfaces.

A fan located in the housing cover constantly cools down the device.

The controller is available in various model variants for SILworX and ELOP II Factory, see Table 4.

The device is suitable for mounting in Ex-zone 2, see Chapter 4.1.5.

The device is TÜV-certified for safety-related applications up to SIL 3 (IEC 61508, IEC 61511 and IEC 62061), Cat. 4 and PL e (EN ISO 13849-1) and SIL 4 (EN 50126, EN 50128 and EN 50129).

Further safety standards, application standards and test standards are specified in the certificates available on the HIMA website.

#### 3.1 Safety Function

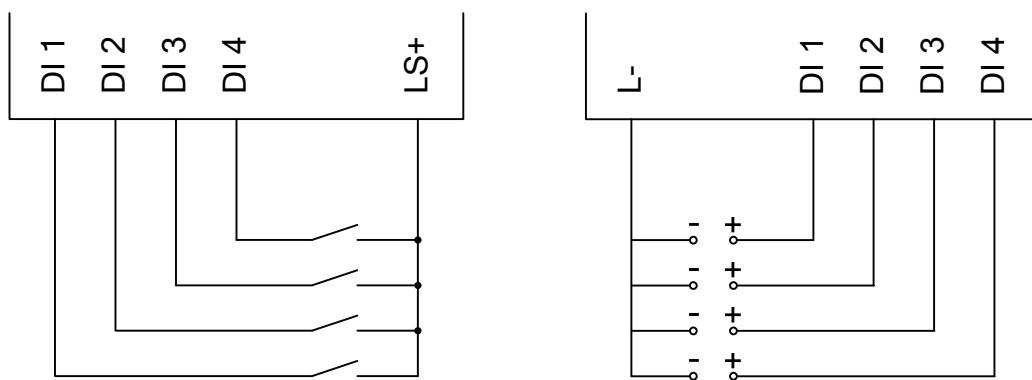
The controller is equipped with 8 safety-related, digital channels (DIO), which can be individually configured as digital input or digital output. The state (HIGH, LOW) of each input is signaled by an individual LED (HIGH, LOW).

##### 3.1.1 Safety-Related Digital Inputs

Mechanical contacts without own power supply or signal power source can be connected to the inputs.

Potential-free mechanical contacts without own power supply are fed via an internal short-circuit-proof 24 V power source (LS+). Each of them supply a group of 4 mechanical contacts. Figure 1 shows how the connection is performed.

With signal voltage sources, the corresponding ground must be connected to the input (L-), see Figure 1.



Connection of potential-free mechanical contacts

Connection of signal power sources

Figure 1: Connections to Safety-Related Digital Inputs

For the external wiring and the connection of sensors, apply the de-energized-to-trip principle. Thus, if a fault occurs, the input signals adopt a de-energized, safe state (low level).

If an external wire is not monitored, an open-circuit is considered as safe low level.

### 3.1.1.1 Reaction in the Event of a Fault

If the device detects a fault on a digital input, the user program processes a low level in accordance with the de-energized to trip principle.

The device activates the *FAULT* LED.

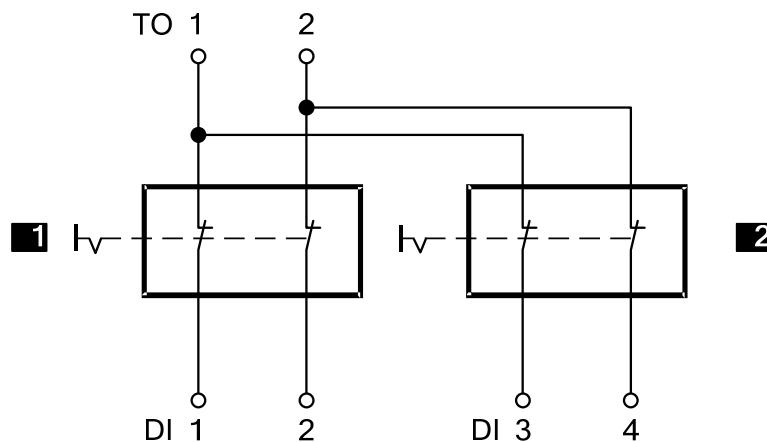
In addition to the channel signal value, the user program must also consider the corresponding error code.

The error code allows the user to configure additional fault reactions in the user program.

### 3.1.1.2 Line Control

Line control is used to detect short-circuits or open-circuits and can be configured for the F20 system, e.g., on EMERGENCY STOP inputs complying with Cat. 4 and PL e in accordance with EN ISO 13849-1.

To this end, connect the pulsed outputs TO 1...TO 4 of the system to the digital inputs DI of the same system as follows:



**1** EMERGENCY STOP 1  
**2** EMERGENCY STOP 2

EMERGENCY STOP switches in accordance with EN 60947-5-1 and EN 60947-5-5

Figure 2: Line Control

The controller pulses the pulsed outputs (TO) to detect short-circuits and open-circuits on lines connected to the digital inputs (DI). To do so, configure the *Value [BOOL] -> system variable* in SILworX or the *DO[01].Value* system signal in ELOP II Factory. The variables for the pulsed outputs must begin with channel 1 and reside in direct sequence, one after the other.

In the programming tool, use an assigned variable to set the *DI Pulse Delay* system variable to at least 500 µs.

If the following faults occur, the *FAULT* LED located on the front plate of the controller blinks, the inputs are set to low level and an (evaluable) error code is created:

- Cross-circuit between two parallel wires.
- Invalid connections of two lines (e.g., TO 2 to DI 3),
- Earth fault on one wire (with earthed ground only).
- Open-circuit or open contacts, i.e., including when one of the two EMERGENCY STOP switches mentioned above has been engaged, the *FAULT* LED blinks and the error code is created.

### 3.1.2 Safety-Related Digital Outputs

The controller is equipped with 8 channels, which can be individually configured as digital input or digital output.

To configure a digital channel as an output in SILworX, use the *Channel [BOOL] -> system* parameter, to configure it in ELOP II Factory, use the *DO[xx].Used* system signal.

The digital channel can only be used as an output, if the value of the corresponding system variable is set to TRUE. The variable of the respective input displays the current output state.

At the maximum ambient temperature, the outputs 1...3 and 5...7 can be loaded with 0.5 A each; and outputs 4 and 8 can be loaded with 1 A or with 2 A at an ambient temperature of up to 50 °C.

If an overload occurs, one or all digital outputs are switched off. If the overload is removed, the outputs are switched on again automatically, see Table 18.

A short-circuit detected on the output is signaled. The external output line, however, is not monitored.

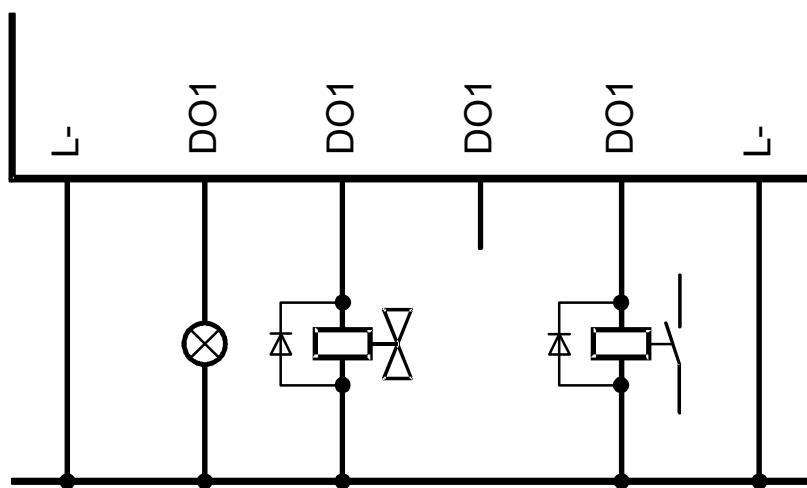


Figure 3: Connection of Actuators to Outputs

The redundant connection of two outputs must be decoupled with diodes.

#### ⚠ WARNING

For connecting a load to a 1-pole switching output, use the corresponding L- ground of the respective channel group (2-pole connection) to ensure that the internal protective circuit can function.



Inductive loads may be connected with no free-wheeling diode on the actuator. However, HIMA strongly recommends connecting a protective diode directly to the actuator.

### 3.1.2.1 Reaction in the Event of a Fault

If the device detects a faulty signal on a digital output, the affected module output is set to the safe (de-energized) state using the safety switches.

If a device fault occurs, all digital outputs are switched off.

In both cases, the device activates the **FAULT LED**.

The error code allows the user to configure additional fault reactions in the user program.

### 3.2 Equipment, Scope of Delivery

The following table specifies the available controller variants:

Designation	Description
F20 01	Controller (8 digital channels, configurable as inputs or outputs, 4 pulsed outputs), Operating temperature: 0...+60 °C, for ELOP II Factory programming tool
F20 01 SILworX	Controller (8 digital channels, configurable as inputs or outputs, 4 pulsed outputs), Operating temperature: 0...+60 °C, for SILworX programming tool

Table 4: Available Variants

#### 3.2.1 IP Address and System ID (SRS)

A transparent label is delivered with the device to allow one to note the IP address and the system ID (SRS for system rack slot) after a change.

IP \_\_\_\_ . \_\_\_\_ . \_\_\_\_ . \_\_\_\_ SRS \_\_\_\_ . \_\_\_\_ . \_\_\_\_

Default value for IP address: 192.168.0.99

Default value for SRS: 60 000.0.0

The label must be affixed such that the ventilation slots in the housing are not obstructed.

Refer to the First Steps manual of the programming tool for more information on how to modify the IP address and the system ID.

### 3.3 Type Label

The type plate contains the following details:

- Product name
- Bar code (1D or 2D code)
- Part no.
- Production year
- Hardware revision index (HW Rev.)
- Firmware revision index (FW Rev.)
- Operating voltage
- Mark of conformity

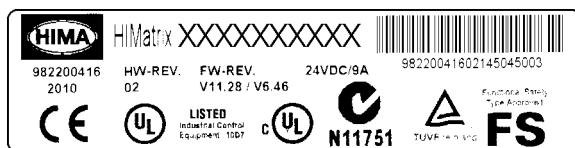


Figure 4: Sample Type Label

### 3.4 Structure

This chapter describes the layout and function of the controller, and its connection for communication.

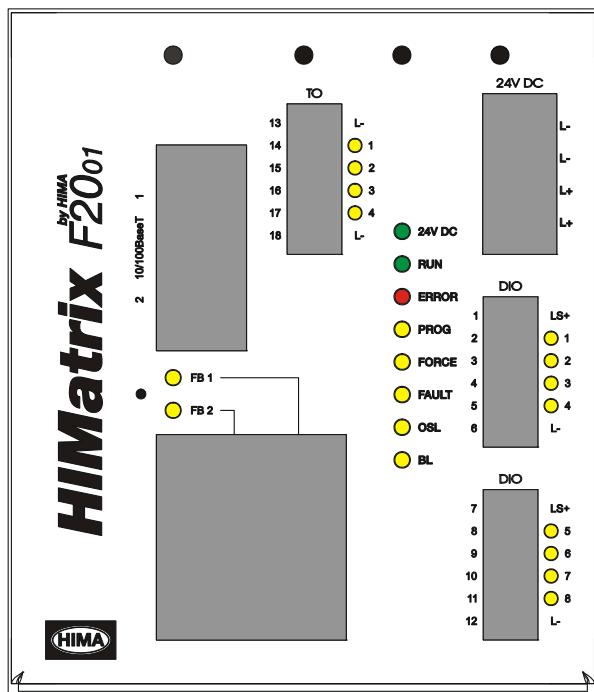


Figure 5: Front View

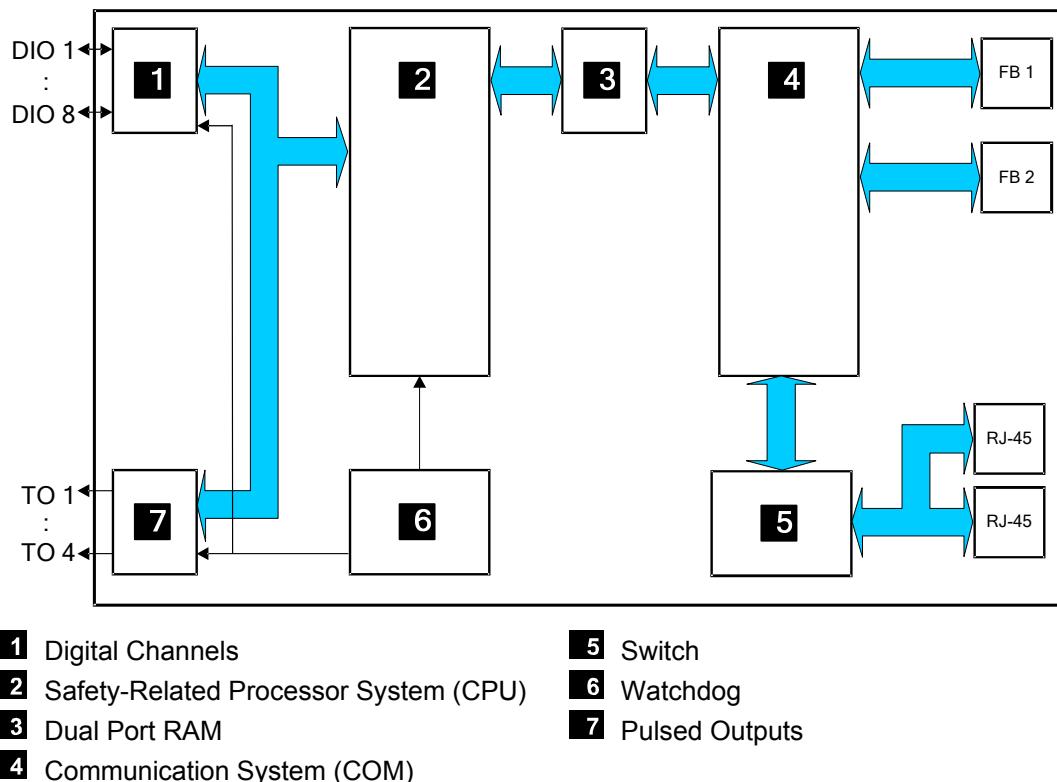


Figure 6: Block Diagram

### 3.4.1 LED Indicators

The light-emitting diodes (LEDs) indicate the operating state of the controller. The LEDs are classified as follows:

- Operating voltage LED
- System LEDs
- Communication LEDs
- I/O LEDs
- Fieldbus LEDs

Function and meaning of the system LEDs and communication LEDs depend on the CPU operating system (and thus on the COM operating system).

When the supply voltage is switched on, a LED test is performed and all LEDs are briefly lit.

#### Definition of Blinking Frequencies

The following table defines the blinking frequencies of the LEDs:

Name	Blinking frequencies
Blinking	Non-specified blinking, with CPU OS up to V7.x
Blinking1	Long (approx. 600 ms) on, long (approx. 600 ms) off, with CPU OS V8 and higher
Blinking-x	Ethernet communication: Blinking synchronously with data transfer, with CPU OS V8 and higher

Table 5: Blinking Frequencies of LEDs

#### 3.4.1.1 Operating Voltage LED

The operating voltage LED does not depend on the CPU operating system in use.

LED	Color	Status	Description
24 VDC	Green	On	24 VDC operating voltage present
		Off	No operating voltage

Table 6: Operating Voltage LED

### 3.4.1.2 System LEDs

#### System LEDs with CPU OS V8 and Higher

While the system is being booted, all LEDs are lit simultaneously.

LED	Color	Status	Description
RUN	Green	On	Device in RUN, normal operation A loaded user program is being processed.
		Blinking1	<ul style="list-style-type: none"> <li>▪ Device in STOP</li> <li>▪ A new operating system is being loaded.</li> </ul>
		Off	The device is not in the RUN or STOP state.
ERROR	Red	On	Missing license for additional functions (communication protocols, reload), test mode.
		Blinking1	<ul style="list-style-type: none"> <li>▪ The device is in the ERROR STOP state. Internal module faults detected by self-tests, e.g., hardware or voltage supply. The processor system can only be restarted with a command from the PADT (reboot).</li> <li>▪ Fault while loading the operating system.</li> </ul>
		Off	No faults detected.
PROG	Yellow	On	<ul style="list-style-type: none"> <li>▪ A new configuration is being loaded into the device.</li> <li>▪ A new operating system is being loaded.</li> <li>▪ WDT or safety time change</li> <li>▪ SRS change</li> </ul>
		Off	None of the described events occurred.
FORCE	Yellow	On	Forcing prepared: The force switch is set for a variable, the force main switch is still deactivated. The device is in the RUN or STOP state.
		Blinking1	Forcing is active: At least one local or global variable has adopted the corresponding force value.
		Off	Forcing is not activated.
FAULT	Yellow	On/Blinking1	<ul style="list-style-type: none"> <li>▪ Fault while loading a new operating system</li> <li>▪ The new operating system is corrupted (after OS download).</li> <li>▪ The loaded configuration is not valid.</li> <li>▪ At least one I/O fault has been detected.</li> </ul>
		Off	None of the described faults occurred.
OSL	Yellow	Blinking1	Operating system emergency loader active.
		Off	Operating system emergency loader not active.
BL	Yellow	On/Blinking1	<ul style="list-style-type: none"> <li>▪ OS and OSL binary defective or INIT_FAIL hardware fault.</li> <li>▪ Fault in the external process data communication.</li> </ul>
		Off	None of the described events occurred.

Table 7: System LEDs with CPU OS V8 and Higher

## System LEDs with CPU OS up to V6.x

While the system is being booted, all LEDs are lit simultaneously.

LED	Color	Status	Description
RUN	Green	On	Device in RUN, normal operation A loaded user program is being processed.
		Blinking	Device in STOP. No user program is being processed.
		Off	The device is in the ERROR STOP state, see ERROR LED.
ERROR	Red	On	Internal module faults detected by self-tests, e.g., hardware or cycle time overrun. The CPU stopped the user program execution, terminated all hardware and software tests and reset all outputs. The processor system can only be restarted with a command from the PADT (reboot).
		Off	No faults detected.
PROG	Yellow	On	A new configuration is being loaded into the device.
		Blinking	A new operating system is being loaded into the flash ROM. The LED also blinks during the device's initialization phase.
		Off	No configuration or operating system is being loaded.
FORCE	Yellow	On	The device is in RUN, forcing was activated.
		Blinking	The device is in STOP, forcing has been prepared and is activated when the device is started.
		Off	Forcing is not activated.
FAULT	Yellow	On	<ul style="list-style-type: none"> <li>▪ Line control fault indicator</li> <li>▪ The user program caused a fault.</li> <li>▪ The device configuration is not valid.</li> <li>▪ Loading of the new operating system was not successful and the operating system is corrupted.</li> </ul>
		Blinking	<ul style="list-style-type: none"> <li>▪ While the operating system was being updated, a fault occurred during the write cycle of a flash ROM.</li> <li>▪ One or multiple I/O faults occurred.</li> </ul>
		Off	None of the described faults occurred.
OSL	Yellow	Blinking	Operating system emergency loader active.
		Off	Operating system emergency loader not active.
BL	Yellow	Blinking	OS and OSL binary defective or hardware fault, INIT_FAIL.
		Off	None of the described faults occurred.

Table 8: System LEDs with CPU OS up to V6

### 3.4.1.3 Communication LEDs

All RJ-45 connectors are provided with a small green and a yellow LEDs.

#### Communication LEDs with CPU OS V8 and Higher

The LEDs signal the following states:

LED	Status	Description
Green	On	Full duplex operation
	Blinking1	IP address conflict, all communication LEDs are blinking
	Blinking-x	Collision
	Off	Half duplex operation, no collision
Yellow	On	Connection available
	Blinking1	IP address conflict, all communication LEDs are blinking
	Blinking-x	Interface activity
	Off	No connection available

Table 9: Ethernet Indicators with CPU OS V8 and Higher

#### Communication LEDs up to CPU OS V6.x

The LEDs signal the following states:

LED	Status	Description
Green	On	Full duplex operation
	Blinking	Collision
	Off	Half duplex operation, no collision
Yellow	On	Connection available
	Blinking	Interface activity
	Off	No connection available

Table 10: Ethernet Indicators up to CPU OS V6.x

### 3.4.1.4 I/O LEDs

LED	Color	Status	Description
DIO 1...8	Yellow	On	The related channel is active (energized).
		Off	The related channel is inactive (de-energized).
TO 1...4	Yellow	On	Pulsed output activated.
		Off	Pulsed output deactivated.

Table 11: I/O LEDs

### 3.4.1.5 Fieldbus LEDs

LEDs FB1 and FB2 are used to display the state of communication occurring via the serial interfaces. The function of the LED depends on the used protocol.

Refer to the corresponding communication manual for more details on the function of the LEDs.

### 3.4.2 Communication

The controller communicates with remote I/Os via **safeEthernet**.

#### 3.4.2.1 Connections for Ethernet Communication

Property	Description
Port	2 x RJ-45
Transfer standard	10BASE-T/100BASE-Tx, half and full duplex
Auto negotiation	Yes
Auto crossover	Yes
IP address	Freely configurable <sup>1)</sup>
Subnet mask	Freely configurable <sup>1)</sup>
Supported protocols	<ul style="list-style-type: none"> <li>▪ Safety-related: <b>safeEthernet</b></li> <li>▪ Standard protocols: Programming and debugging tool (PADT), OPC, Modbus TCP, TCP-SR, SNTP, Ethernet/IP<sup>2)</sup></li> </ul>

<sup>1)</sup> The general rules for assigning IP address and subnet masks must be adhered to.  
<sup>2)</sup> EtherNet/IP is not supported in SILworX.

Table 12: Ethernet Interfaces Properties

The two RJ-45 connectors with integrated LEDs are located on the bottom left-hand side of the housing. Refer to Chapter 3.4.1.3 for a description of the LEDs' function.

The connection parameters are read based on the MAC address (media access control address) defined during manufacturing.

The MAC address for controller is specified on a label located above the two RJ-45 connectors (1 and 2).

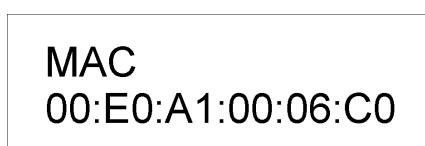


Figure 7: Sample MAC Address Label

The controller is equipped with an integrated switch for Ethernet communication. For further information on the integrated switch and **safeEthernet**, refer to Chapter *Communication* of the system manual for compact systems (HI 800 141 E).

### 3.4.2.2 Network Ports Used for Ethernet Communication

UDP ports	Use
8000	Programming and operation with the programing tool
8001	Configuration of the remote I/O using the PES (ELOP II Factory)
8004	Configuration of the remote I/O using the PES (SILworX)
6010	safeEthernet and OPC
123	SNTP (time synchronization between PES and remote I/O, PES and external devices)
6005 / 6012	If TCS_DIRECT was not selected in the HH network
502	Modbus (can be modified by the user)
44 818	EtherNet/IP session protocol for device identification
2222	EtherNet/IP data exchange

Table 13: Network Ports (UDP Ports) in Use

TCP ports	Use
502	Modbus (can be modified by the user)
xxx	TCP SR assigned by the user
44 818	EtherNet/IP explicit messaging services

Table 14: Network Ports (TCP Ports) in Use

### 3.4.2.3 Connections for Fieldbus Communication

The two 9-pole D-sub connectors are located on the front plate of the housing.

The fieldbus interface FB1 can be equipped with a fieldbus submodule. The fieldbus submodules are optional and must be mounted by the manufacturer. The available fieldbus submodules are described in the SILworX communication manual (HI 801 101 E).

The fieldbus interface is not operational without fieldbus submodule.

Factory-made, the fieldbus interface FB2 is equipped with RS485 for Modbus (master or slave) or ComUserTask.

### 3.4.3 Reset Key

The controller is equipped with a reset key. The key is only required if the user name or password for administrator access is not known. If only the IP address set for the controller does not match the PADT (PC), the connection can be established with a `Route add` entry on the PC.

The key can be accessed through a small round hole located approximately 5 cm from the upper left-hand side of the housing. The key is engaged using a suitable pin made of insulating material to avoid short-circuits within the controller.

The reset is only effective if the controller is rebooted (switched off and on) while the key is simultaneously engaged for at least 20 s. Engaging the key during operation has no effect.

#### ⚠ CAUTION



**Fieldbus communication may be disturbed!**

**Prior to switching on the controller with the reset key engaged, all device fieldbus connectors must be unplugged to ensure that the fieldbus communication among other stations is not disturbed.**

**The fieldbus plugs may only be plugged in again when the controller is in the RUN or STOP state.**

Properties and behavior of the controller after a reboot with engaged reset key:

- Connection parameters (IP address and system ID) are set to the default values.
- All accounts are deactivated except for the *administrator* default account with empty password.
- With COM operating system version 10.42 and higher, loading a user program or operating system with default connection parameters is inhibited!  
The loading procedure is only allowed after the connection parameters and the account have been configured on the controller and the controller has been rebooted.

After a new reboot without the reset key engaged, the connection parameters (IP address and system ID) and accounts become effective.

- Those configured by the user.
- Those valid prior to rebooting with the reset key engaged, if no changes were performed.

### 3.4.4 Fan

The printed circuit boards in the F20 must be actively cooled. To this end, a Papst fan of type 614 F is mounted in the housing cover. The fan has a life time of approximately 20 000 hours at an operating temperature of 60 °C.

In the PADT loaded with a programming tool, the *Fan State* system parameter can be used to evaluate the fan states (0 = fan is operating, 1 = fan is faulty).

Depending on the temperature state around the power supply unit for the F20, the fan is controlled in two steps:

Temperature state	Fan state
< 45 °C	Normal (fan ON)
≥ 45 °C	Highest operating speed

Table 15: Fan State

#### 3.4.4.1 Replacing the Fan

The fan may only be replaced by HIMA service.

**i** The fan may be replaced on site by HIMA service personnel. To do so, the controller must be switched off. The warranty is voided if the device is opened by the customer.

#### 3.4.4.2 Replacement Interval

- At normal temperatures ( $< 40$  °C): every 5 years
- At increased temperatures ( $\geq 40$  °C): every 3 years

### 3.4.5 Hardware Clock

In case of loss of operating voltage, the power provided by an integrated gold capacitor is sufficient to buffer the hardware clock for approximately one week.

### 3.5 Product Data

General		
User memory	Versions prior to 6.46	max. 500 kB user program max. 500 kB user data
	Version 6.100	max. 2047 kB user program max. 2047 kB user data
	Version 7 and higher	max. 1023 kB user program max. 1023 kB user data
Response time	≥ 10 ms	
Ethernet interfaces	2 x RJ-45, 10BASE-T/100BASE-Tx with integrated switch	
Fieldbus interfaces	2 x 9-pole D-sub FB1 with fieldbus submodule pluggable, FB2 with RS485 for Modbus (master or slave) or ComUserTask	
Operating voltage	24 VDC, -15...+20 %, $r_{PP} \leq 15 \%$ , from a power supply unit with safe insulation in accordance with IEC 61131-2	
Current input	max. 8 A (with maximum load) Idle: 0.5 A	
Fuse (external)	10 A time-lag (T)	
Buffer for date/time	Gold capacitor	
Operating temperature	0...+60 °C	
Storage temperature	-40...+85 °C	
Type of protection	IP20	
Max. dimensions (without plug)	Width: 95 mm (with housing screws) Height: 114 mm (with fixing bolt) Depth: 140 mm (with earthing screw)	
Weight	approx. 750 g	

Table 16: Product Data

Digital inputs	
Number of inputs	8 (non-galvanically separated)
High level: Voltage	15...30 VDC
Current input	≥ 2 mA at 15 V
Low level: Voltage	max. 5 VDC
Current input	max. 1.5 mA (1 mA at 5 V)
Switching point	typ. 7.5 V
Sensor supply LS+	2 x 20 V / 100 mA (at 24 V), short-circuit-proof

Table 17: Specifications for Digital Inputs

Digital outputs							
Number of outputs	8 (non-galvanically separated)						
Output voltage	$\geq L+$ minus 2 V						
Output current	Channels 1...3 and 5...7: 0.5 A up to 60 °C The output current of the channels 4 and 8 depends on the ambient temperature. <table border="1" data-bbox="759 399 1422 512"> <thead> <tr> <th>Ambient temperature</th><th>Output current</th></tr> </thead> <tbody> <tr> <td>&lt; 50 °C</td><td>2 A</td></tr> <tr> <td>50...60 °C</td><td>1 A</td></tr> </tbody> </table>	Ambient temperature	Output current	< 50 °C	2 A	50...60 °C	1 A
Ambient temperature	Output current						
< 50 °C	2 A						
50...60 °C	1 A						
Minimum load	2 mA for each channel						
Internal voltage drop	max. 2 V at 2 A						
Leakage current (with low level)	max. 1 mA at 2 V						
Behavior upon overload	The affected output is switched off and cyclically switched on again						
Total output current	max. 7 A Upon overload, all outputs are switched off and cyclically switched on again						

Table 18: Specifications for the Digital Outputs

Pulsed outputs	
Number of outputs	4 (non-galvanically separated)
Output voltage	approx. 20 V (depending on the operating voltage)
Output current	approx. 60 mA
Minimum load	none
Behavior upon overload	4 x $\geq 19.2$ V, short-circuit current 60 mA at 24 V

Table 19: Specifications for the Pulsed Outputs

### 3.6 Certified HIMatrix F20

HIMatrix F20	
CE	EMC, ATEX Zone 2
TÜV	IEC 61508 1-7:2000 up to SIL 3 IEC 61511:2004 EN ISO 13849-1:2008 up to Cat. 4 und PL e
UL Underwriters Laboratories Inc.	ANSI/UL 508, NFPA 70 – Industrial Control Equipment CSA C22.2 No.142 UL 1998 Software Programmable Components NFPA 79 Electrical Standard for Industrial Machinery IEC 61508
FM Approvals	Class I, DIV 2, Groups A, B, C and D Class 3600, 1998 Class 3611, 1999 Class 3810, 1989 Including Supplement #1, 1995 CSA C22.2 No. 142 CSA C22.2 No. 213
PROFIBUS Nutzerorganisation (PNO)	Test Specification for PROFIBUS DP Slave, Version 3.0 November 2005
TÜV CENELEC	Railway applications EN 50126: 1999 up to SIL 4 EN 50128: 2001 up to SIL 4 EN 50129: 2003 up to SIL 4

Table 20: Certificates

## 4 Start-up

To start up the controller, it must be mounted, connected and configured in the programming tool.

### 4.1 Installation and Mounting

The controller is mounted on a 35 mm DIN rail such as described in the system manual for compact systems.

When laying cables (long cables, in particular), take appropriate measures to avoid interference, e.g., by separating the signal lines from the power lines.

When dimensioning the cables, ensure that their electrical properties have no negative impact on the measuring circuit.

#### 4.1.1 Connecting the Digital Inputs

Use the following terminals to connect the digital inputs:

Terminal	Designation	Function (inputs DI)
1	LS+	Sensor supply of the inputs 1...4
2	1	Digital input 1
3	2	Digital input 2
4	3	Digital input 3
5	4	Digital input 4
6	L-	Ground
Terminal	Designation	Function (inputs DI)
7	LS+	Sensor supply of the inputs 5...8
8	5	Digital input 5
9	6	Digital input 6
10	7	Digital input 7
11	8	Digital input 8
12	L-	Ground

Table 21: Terminal Assignment for the Digital Inputs

##### 4.1.1.1 Surges on Digital Inputs

Due to the short cycle time of the HIMatrix systems, a surge pulse as described in EN 61000-4-5 can be read in to the digital inputs as a short-term high level.

The following measures ensure proper operation in environments where surges may occur:

1. Install shielded input wires
2. Program noise blanking in the user program. A signal must be present for at least two cycles before it is evaluated. The fault reaction is triggered with a corresponding delay.



The measures specified above are not necessary if the plant design precludes surges from occurring within the system.

In particular, the design must include protective measures with respect to overvoltage, lightning, earth grounding and plant wiring in accordance with the relevant standards and the instructions specified in the system manual (HI 800 141 E or HI 800 191 E).

#### 4.1.2 Connecting the Digital Outputs

Use the following terminals to connect the digital outputs:

Terminal	Designation	Function (outputs DO)
1	LS+	---
2	1	Digital input/output 1
3	2	Digital input/output 2
4	3	Digital input/output 3
5	4	Digital input/output 4
6	L-	Ground channel group
Terminal	Designation	Function (inputs DI)
7	LS+	---
8	5	Digital input/output 5
9	6	Digital input/output 6
10	7	Digital input/output 7
11	8	Digital input/output 8
12	L-	Ground channel group

Table 22: Terminal Assignment for the Digital Outputs

#### 4.1.3 Connecting Pulsed Outputs

Terminal assignment for the pulsed outputs.

Terminal	Designation	Function (pulsed outputs TO)
13	L-	Ground
14	1	Pulsed output 1
15	2	Pulsed output 2
16	3	Pulsed output 3
17	4	Pulsed output 4
18	L-	Ground

Table 23: Terminal Assignment for the Pulsed Outputs

#### 4.1.4 Cable Plugs

Cable plugs attached to the pin headers of the devices are used to connect to the power supply and to the field zone. The cable plugs are included within the scope of delivery of the HIMatrix devices and modules.

The devices power supply connections feature the following properties:

Connection to the power supply	
Cable plugs	Four poles, screw terminals
Wire cross-section	0.2...2.5 mm <sup>2</sup> (single-wire) 0.2...2.5 mm <sup>2</sup> (finely stranded) 0.2...2.5 mm <sup>2</sup> (with wire end ferrule)
Stripping length	10 mm
Screwdriver	Slotted 0.6 x 3.5 mm
Tightening torque	0.4...0.5 Nm

Table 24: Power Supply Cable Plug Properties

Connection to the field zone	
Number of cable plugs	3 pieces, six poles, screw terminals
Wire cross-section	0.2...1.5 mm <sup>2</sup> (single-wire) 0.2...1.5 mm <sup>2</sup> (finely stranded) 0.2...1.5 mm <sup>2</sup> (with wire end ferrule)
Stripping length	6 mm
Screwdriver	Slotted 0.4 x 2.5 mm
Tightening torque	0.2...0.25 Nm

Table 25: Input and Output Cable Plug Properties

#### 4.1.5 Mounting the F20 in Zone 2

(EC Directive 94/9/EC, ATEX)

The controller is suitable for mounting in zone 2. Refer to the corresponding declaration of conformity available on the HIMA website.

When mounting the device, observe the special conditions specified in the following section.

##### Specific Conditions X

1. Mount the HIMatrix F20 controller in an enclosure that meets the EN 60079-15 requirements and achieves a type of protection of at least IP54, in accordance with EN 60529. Provide the enclosure with the following label:

##### **Work is only permitted in the de-energized state**

Exception:

If a potentially explosive atmosphere has been precluded, work can also be performed when the controller is under voltage.

2. The enclosure in use must be able to safely dissipate the generated heat. Depending on the output load and supply voltage, the HIMatrix F20 has a power dissipation ranging between 12 W and 29 W.
3. Protect the HIMatrix F20 with a 10 A time-lag fuse.  
The 24 VDC power must come from a power supply unit with safe isolation. Use power supply units of type PELV or SELV only.
4. Applicable standards:  
VDE 0170/0171 Part 16, DIN EN 60079-15: 2004-5  
VDE 0165 Part 1, DIN EN 60079-14: 1998-08

Pay particular attention to the following sections:

DIN EN 60079-15:

Chapter 5	Design
Chapter 6	Terminals and cabling
Chapter 7	Air and creeping distances
Chapter 14	Connectors

DIN EN 60079-14:

Chapter 5.2.3	Equipment for use in zone 2
Chapter 9.3	Cabling for zones 1 and 2
Chapter 12.2	Equipment for zones 1 and 2

The controller is additionally equipped with the label represented below:

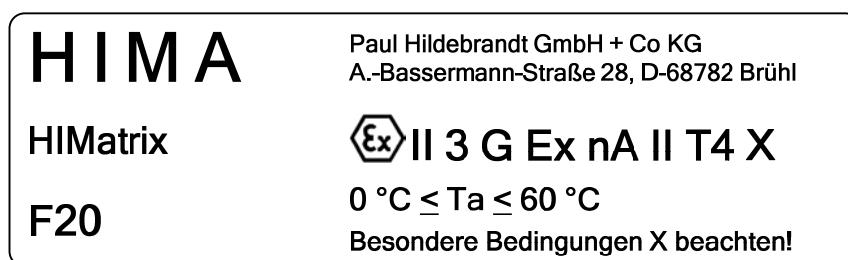


Figure 8: Label for Ex Conditions

## 4.2 Configuration

The controller can be configured using a programming tool, SILworX or ELOP II Factory. Which programming tool should be used, depends on the revision status of the operating system (firmware):

- SILworX is required for CPU OS V7 and higher.
- ELOP II Factory is required for CPU OS up to V6.x.



How to switch between operating systems is described in Chapter *Loading Operating Systems* of the system manual for compact systems (HI 800 141 E).

## 4.3 Configuration with SILworX

In the Hardware Editor, the controller is represented like a base plate equipped with the following modules:

- Processor module (CPU)
- Communication module (COM)
- Input and output module (DIO 8/8)
- Output module (DO 4)

Double-click the module to open the Detail View with the corresponding tabs. The tabs are used to assign the global variables configured in the user program to the system variables of the corresponding module.

### 4.3.1 Parameters and Error Codes for the Inputs and Outputs

The following tables specify the system parameters that can be read and set for the inputs and outputs, including the corresponding error codes.

In the user program, the error codes can be read using the variables assigned within the logic.

The error codes can also be displayed in SILworX.

### 4.3.2 Digital Inputs and Outputs for F20

The following tables present the statuses and parameters for the digital input and output module (DIO 8/8) in the same order as given in the Hardware Editor.

#### 4.3.2.1 Tab: **Module**

The **Module** tab contains the following system parameters:

System parameter	Data type	R/W	Description																								
DI number of pulsed channels	USINT	W	<p>Number of pulsed outputs (supply outputs)</p> <table border="1"> <thead> <tr> <th>Coding</th><th>Description</th></tr> </thead> <tbody> <tr> <td>0</td><td>No pulsed output planned for SC/OC<sup>1)</sup> detection</td></tr> <tr> <td>1</td><td>Pulsed output 1 planned for SC/OC<sup>1)</sup> detection</td></tr> <tr> <td>2</td><td>Pulsed output 1 and 2 planned for SC/OC<sup>1)</sup> detection</td></tr> <tr> <td>3</td><td>Pulsed outputs 1, 2 and 3 planned for SC/OC<sup>1)</sup> detection</td></tr> <tr> <td>4</td><td>Pulsed outputs 1...4 planned for SC/OC<sup>1)</sup> detection</td></tr> </tbody> </table> <p><b>Pulsed outputs must not be used as safety-related outputs!</b></p>	Coding	Description	0	No pulsed output planned for SC/OC <sup>1)</sup> detection	1	Pulsed output 1 planned for SC/OC <sup>1)</sup> detection	2	Pulsed output 1 and 2 planned for SC/OC <sup>1)</sup> detection	3	Pulsed outputs 1, 2 and 3 planned for SC/OC <sup>1)</sup> detection	4	Pulsed outputs 1...4 planned for SC/OC <sup>1)</sup> detection												
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0	No pulsed output planned for SC/OC <sup>1)</sup> detection																										
1	Pulsed output 1 planned for SC/OC <sup>1)</sup> detection																										
2	Pulsed output 1 and 2 planned for SC/OC <sup>1)</sup> detection																										
3	Pulsed outputs 1, 2 and 3 planned for SC/OC <sup>1)</sup> detection																										
4	Pulsed outputs 1...4 planned for SC/OC <sup>1)</sup> detection																										
DI Pulse Slot	UDINT	W	Pulse module slot (SC/OC <sup>1)</sup> detection), set the value to 2																								
DI Pulse Delay [μs]	UINT	W	<p>Waiting time for line control (detection of short-circuits or cross-circuits)</p> <p>The initial value for the <i>DI Pulse Delay</i> system parameter in SILworX must be set to at least 500 μs.</p>																								
DI.Error Code	WORD	R	<p>Error codes for all digital inputs</p> <table border="1"> <thead> <tr> <th>Coding</th><th>Description</th></tr> </thead> <tbody> <tr> <td>0x0001</td><td>Fault within the digital inputs</td></tr> <tr> <td>0x0002</td><td>FTT test of test pattern faulty</td></tr> </tbody> </table>	Coding	Description	0x0001	Fault within the digital inputs	0x0002	FTT test of test pattern faulty																		
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0x0800	FTT test: 2nd temperature threshold exceeded																										
0x1000	FTT test: Monitoring of auxiliary voltage 1: Undervoltage																										

System parameter	Data type	R/W	Description																
Module Error Code	WORD	R	Module error code <table border="1" style="margin-left: 10px;"> <tr> <th>Coding</th> <th>Description</th> </tr> <tr> <td>0x0000</td> <td>I/O processing, if required with errors see other error codes</td> </tr> <tr> <td>0x0001</td> <td>No I/O processing (CPU not in RUN)</td> </tr> <tr> <td>0x0002</td> <td>No I/O processing during the booting test</td> </tr> <tr> <td>0x0004</td> <td>Manufacturer interface operating</td> </tr> <tr> <td>0x0010</td> <td>No I/O processing: invalid configuration</td> </tr> <tr> <td>0x0020</td> <td>No I/O processing: fault rate exceeded</td> </tr> <tr> <td>0x0040/ 0x0080</td> <td>No I/O processing: configured module not plugged in</td> </tr> </table>	Coding	Description	0x0000	I/O processing, if required with errors see other error codes	0x0001	No I/O processing (CPU not in RUN)	0x0002	No I/O processing during the booting test	0x0004	Manufacturer interface operating	0x0010	No I/O processing: invalid configuration	0x0020	No I/O processing: fault rate exceeded	0x0040/ 0x0080	No I/O processing: configured module not plugged in
Coding	Description																		
0x0000	I/O processing, if required with errors see other error codes																		
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0x0004	Manufacturer interface operating																		
0x0010	No I/O processing: invalid configuration																		
0x0020	No I/O processing: fault rate exceeded																		
0x0040/ 0x0080	No I/O processing: configured module not plugged in																		
Module.SRS	[UDINT]	R	Slot number (System Rack Slot)																
Module.Type	[UINT]	R	Type of module, target value: 0x00A6 [166 <sub>dec</sub> ]																
<sup>1)</sup> SC/OC (SC = short-circuit, OC = open-circuit)																			

Table 26: SILworX - System Parameters for Digital Inputs, **Module** Tab

#### 4.3.2.2 Tab: DIO 8/8: DO Channels

The **DIO 8/8: DO Channels** tab contains the following system parameters:

System parameter	Data type	R/W	Description												
Channel no.	---	R	Channel number, defined by default												
-> Error Code [BYTE]	BYTE	R	Error codes for the digital output channels <table border="1" style="margin-left: 10px;"> <tr> <th>Coding</th> <th>Description</th> </tr> <tr> <td>0x01</td> <td>Fault in the digital output module</td> </tr> <tr> <td>0x02</td> <td>Channel shutdown due to overload</td> </tr> <tr> <td>0x04</td> <td>Error while reading back the digital outputs</td> </tr> <tr> <td>0x08</td> <td>Error while reading back the status of the digital outputs</td> </tr> <tr> <td>0x20</td> <td>Impossible to activate the output (invalid configuration)</td> </tr> </table>	Coding	Description	0x01	Fault in the digital output module	0x02	Channel shutdown due to overload	0x04	Error while reading back the digital outputs	0x08	Error while reading back the status of the digital outputs	0x20	Impossible to activate the output (invalid configuration)
Coding	Description														
0x01	Fault in the digital output module														
0x02	Channel shutdown due to overload														
0x04	Error while reading back the digital outputs														
0x08	Error while reading back the status of the digital outputs														
0x20	Impossible to activate the output (invalid configuration)														
Value [BOOL] ->	BOOL	W	Output value for DO channels: 1 = output energized 0 = output de-energized												
Channel Used [BOOL] ->	BOOL	W	Configuration of the digital channels as input or output: 1 = The digital channel is used as output 0 = The digital channel is used as input												

Table 27: SILworX - System Parameters for Digital Inputs, **DIO 8/8: DO Channels** Tab

#### 4.3.2.3 Tab: DIO 8/8: DI Channels

The **DIO 8/8: DI Channels** tab contains the following system parameters:

System parameter	Data type	R/W	Description												
Channel no.	---	R	Channel number, defined by default												
-> Error Code [BYTE]	BYTE	R	Error codes for the digital input channels <table border="1" data-bbox="679 393 1426 662"> <thead> <tr> <th>Coding</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0x01</td> <td>Fault in the analog input module</td> </tr> <tr> <td>0x10</td> <td>Short-circuit of the channel</td> </tr> <tr> <td>0x80</td> <td>Intermittence between pulsed output TO and digital input DI, e.g.,             <ul style="list-style-type: none"> <li>▪ Open-circuit</li> <li>▪ Open switch</li> <li>▪ L+ undervoltage</li> </ul> </td> </tr> </tbody> </table>	Coding	Description	0x01	Fault in the analog input module	0x10	Short-circuit of the channel	0x80	Intermittence between pulsed output TO and digital input DI, e.g., <ul style="list-style-type: none"> <li>▪ Open-circuit</li> <li>▪ Open switch</li> <li>▪ L+ undervoltage</li> </ul>				
Coding	Description														
0x01	Fault in the analog input module														
0x10	Short-circuit of the channel														
0x80	Intermittence between pulsed output TO and digital input DI, e.g., <ul style="list-style-type: none"> <li>▪ Open-circuit</li> <li>▪ Open switch</li> <li>▪ L+ undervoltage</li> </ul>														
-> Value [BOOL]	BOOL	R	Input values for the digital input channels 0 = input de-energized 1 = input energized												
Pulsed Output [USINT] ->	USINT	W	Source channel for pulsed supply <table border="1" data-bbox="679 819 1426 1035"> <thead> <tr> <th>Coding</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Input channel</td> </tr> <tr> <td>1</td> <td>Pulse of the 1st TO channel</td> </tr> <tr> <td>2</td> <td>Pulse of the 2nd TO channel</td> </tr> <tr> <td>3</td> <td>Pulse of the 3rd TO channel</td> </tr> <tr> <td>4</td> <td>Pulse of the 4th TO channel</td> </tr> </tbody> </table>	Coding	Description	0	Input channel	1	Pulse of the 1st TO channel	2	Pulse of the 2nd TO channel	3	Pulse of the 3rd TO channel	4	Pulse of the 4th TO channel
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1	Pulse of the 1st TO channel														
2	Pulse of the 2nd TO channel														
3	Pulse of the 3rd TO channel														
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Table 28: SILworX - System Parameters for Digital Inputs, **DIO 8/8: DI Channels** Tab

### 4.3.3 Pulsed Outputs for F20

The following tables present the statuses and parameters for the pulsed output module (DO 4) in the same order as given in the Hardware Editor.

#### 4.3.3.1 Tab: **Module**

The **Module** tab contains the following system parameters:

System parameter	Data type	R/W	Description																
DO.Error Code	WORD	R	Error code of the TO unit as a whole: <table border="1"> <tr> <td>Coding</td> <td>Description</td> </tr> <tr> <td>0x0001</td> <td>Error of the TO unit as a whole:</td> </tr> </table>	Coding	Description	0x0001	Error of the TO unit as a whole:												
Coding	Description																		
0x0001	Error of the TO unit as a whole:																		
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0x0020	No I/O processing: fault rate exceeded																		
0x0040/ 0x0080	No I/O processing: configured module not plugged in																		
Module SRS	UDINT	R	Slot number (System Rack Slot)																
Module Type	UINT	R	Type of module, target value: 0x00B5 [181 <sub>dec</sub> ]																

Table 29: SILworX - System Parameters for Pulsed Outputs, **Module** Tab

#### 4.3.3.2 Tab: **DO 4: Channels**

The **DO 4: Channels** tab contains the following system parameters.

System parameter	Data type	R/W	Description				
Channel no.	---	R	Channel number, defined by default				
-> Error Code [BYTE]	BYTE	R	Error code of the individual digital pulsed output channels: <table border="1"> <tr> <td>Coding</td> <td>Description</td> </tr> <tr> <td>0x01</td> <td>Fault in the digital pulsed output module</td> </tr> </table>	Coding	Description	0x01	Fault in the digital pulsed output module
Coding	Description						
0x01	Fault in the digital pulsed output module						
Value [BOOL] ->	BOOL	W	Output value for DO channels: 1 = output energized 0 = output de-energized  <b>Pulsed outputs must not be used as safety-related outputs!</b>				

Table 30: SILworX - System Parameters for Pulsed Outputs, **DO 4: Channels** Tab

## 4.4 Configuration with ELOP II Factory

### 4.4.1 Configuring the Inputs and Outputs

The signals previously defined in the Signal Editor (Hardware Management) are assigned to the individual channels (inputs and outputs) using ELOP II Factory. Refer to the system manual for compact systems or the online help for more details.

The following chapter describes the system signals used for assigning signals in the controller.

### 4.4.2 Signals and Error Codes for the Inputs and Outputs

The following tables specify the signals that can be read and set for the inputs and outputs, including the corresponding error codes.

In the user program, the error codes can be read using the signals assigned within the logic.

The error codes can also be displayed in ELOP II Factory.

## 4.4.3 Digital Inputs for F20

System Signal	R/W	Description																
Mod.SRS [UDINT]	R	Slot number (System Rack Slot)																
Mod. Type [UINT]	R	Type of module, target value: 0x00A6 [166 <sub>dec</sub> ]																
Mod. Error Code [WORD]	R	<p>Module error code</p> <table border="1"> <thead> <tr> <th>Coding</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0x0000</td> <td>I/O processing, if required with errors see other error codes</td> </tr> <tr> <td>0x0001</td> <td>No I/O processing (CPU not in RUN)</td> </tr> <tr> <td>0x0002</td> <td>No I/O processing during the booting test</td> </tr> <tr> <td>0x0004</td> <td>Manufacturer interface operating</td> </tr> <tr> <td>0x0010</td> <td>No I/O processing: invalid configuration</td> </tr> <tr> <td>0x0020</td> <td>No I/O processing: fault rate exceeded</td> </tr> <tr> <td>0x0040/ 0x0080</td> <td>No I/O processing: configured module not plugged in</td> </tr> </tbody> </table>	Coding	Description	0x0000	I/O processing, if required with errors see other error codes	0x0001	No I/O processing (CPU not in RUN)	0x0002	No I/O processing during the booting test	0x0004	Manufacturer interface operating	0x0010	No I/O processing: invalid configuration	0x0020	No I/O processing: fault rate exceeded	0x0040/ 0x0080	No I/O processing: configured module not plugged in
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DI.Error Code [WORD]	R	<p>Error codes for all digital inputs</p> <table border="1"> <thead> <tr> <th>Coding</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0x0001</td> <td>Fault within the digital inputs</td> </tr> <tr> <td>0x0002</td> <td>FTT test of test pattern faulty</td> </tr> </tbody> </table>	Coding	Description	0x0001	Fault within the digital inputs	0x0002	FTT test of test pattern faulty										
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DI[xx].Value [BOOL]	R	<p>Input values for the digital input channels. If the digital channel is used as an output, this field displays the current output state.</p> <p>0 = input de-energized 1 = input energized</p>																
DI Number of Pulsed Channels [USINT]	W	<p>Number of pulsed outputs (supply outputs)</p> <table border="1"> <thead> <tr> <th>Coding</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>No pulsed output planned for SC/OC<sup>1)</sup> detection</td> </tr> <tr> <td>1</td> <td>Pulsed output 1 planned for SC/OC<sup>1)</sup> detection</td> </tr> <tr> <td>2</td> <td>Pulsed output 1 and 2 planned for SC/OC<sup>1)</sup> detection</td> </tr> <tr> <td>3</td> <td>Pulsed outputs 1, 2 and 3 planned for SC/OC<sup>1)</sup> detection</td> </tr> <tr> <td>4</td> <td>Pulsed outputs 1...4 planned for SC/OC<sup>1)</sup> detection</td> </tr> </tbody> </table> <p><b>Pulsed outputs must not be used as safety-related outputs!</b></p>	Coding	Description	0	No pulsed output planned for SC/OC <sup>1)</sup> detection	1	Pulsed output 1 planned for SC/OC <sup>1)</sup> detection	2	Pulsed output 1 and 2 planned for SC/OC <sup>1)</sup> detection	3	Pulsed outputs 1, 2 and 3 planned for SC/OC <sup>1)</sup> detection	4	Pulsed outputs 1...4 planned for SC/OC <sup>1)</sup> detection				
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4	Pulsed outputs 1...4 planned for SC/OC <sup>1)</sup> detection																	
DI Pulse Slot [UDINT]	W	Pulse module slot (SC/OC <sup>1)</sup> detection), set the value to 2																

System signal	R/W	Description												
DI[xx].Pulsed Output [USINT]	W	<p>Source channel for pulsed supply</p> <table border="1"> <thead> <tr> <th>Coding</th><th>Description</th></tr> </thead> <tbody> <tr> <td>0</td><td>Input channel</td></tr> <tr> <td>1</td><td>Pulse of the 1st TO channel</td></tr> <tr> <td>2</td><td>Pulse of the 2nd TO channel</td></tr> <tr> <td>3</td><td>Pulse of the 3rd TO channel</td></tr> <tr> <td>4</td><td>Pulse of the 4th TO channel</td></tr> </tbody> </table>	Coding	Description	0	Input channel	1	Pulse of the 1st TO channel	2	Pulse of the 2nd TO channel	3	Pulse of the 3rd TO channel	4	Pulse of the 4th TO channel
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2	Pulse of the 2nd TO channel													
3	Pulse of the 3rd TO channel													
4	Pulse of the 4th TO channel													
DI Pulse Delay [10E-6s] [UINT]	W	<p>Waiting time for line control (detection of short-circuits or cross-circuits) Use an assign signal to set the default initial value (400 µs) of the <i>DI Pulse Delay</i> system signal in ELOP II Factory to at least 500 µs.</p>												
<sup>1)</sup> SC/OC (SC = short-circuit, OC = open-circuit)														

Table 31: ELOP II Factory - Digital Input System Signals

## 4.4.4 Digital Outputs for F20

System Signal	R/W	Description																								
Mod.SRS [UDINT]	R	Slot number (System Rack Slot)																								
Mod. Type [UINT]	R	Type of module, target value: 0x00A6 [166 <sub>dec</sub> ]																								
Mod. Error Code [WORD]	R	<p>Module error code</p> <table border="1"> <thead> <tr> <th>Coding</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0x0000</td> <td>I/O processing, if required with errors, see other error codes</td> </tr> <tr> <td>0x0001</td> <td>No I/O processing (CPU not in RUN)</td> </tr> <tr> <td>0x0002</td> <td>No I/O processing during the booting test</td> </tr> <tr> <td>0x0004</td> <td>Manufacturer interface operating</td> </tr> <tr> <td>0x0010</td> <td>No I/O processing: invalid configuration</td> </tr> <tr> <td>0x0020</td> <td>No I/O processing: fault rate exceeded</td> </tr> <tr> <td>0x0040/ 0x0080</td> <td>No I/O processing: configured module not plugged in</td> </tr> </tbody> </table>	Coding	Description	0x0000	I/O processing, if required with errors, see other error codes	0x0001	No I/O processing (CPU not in RUN)	0x0002	No I/O processing during the booting test	0x0004	Manufacturer interface operating	0x0010	No I/O processing: invalid configuration	0x0020	No I/O processing: fault rate exceeded	0x0040/ 0x0080	No I/O processing: configured module not plugged in								
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DO[xx].Value [BOOL]	W	<p>Output value for DO channels:</p> <p>1 = output energized 0 = output de-energized</p>																								
DO[xx].Used [BOOL]	W	<p>Configuration of the digital channels as input or output:</p> <p>1 = The digital channel is used as output 0 = The digital channel is used as input (default setting)</p>																								

Table 32: ELOP II Factory - Digital Output System Signals

## 4.4.5 Pulsed Outputs for F20

System Signal	R/W	Description																
Mod.SRS [UDINT]	R	Slot number (System Rack Slot)																
Mod. Type [UINT]	R	Type of module, target value: 0x00B5 [181 <sub>dec</sub> ]																
Mod. Error Code [WORD]	R	<p>Module error code</p> <table border="1"> <thead> <tr> <th>Coding</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0x0000</td> <td>I/O processing, if required with errors, see other error codes</td> </tr> <tr> <td>0x0001</td> <td>No I/O processing (CPU not in RUN)</td> </tr> <tr> <td>0x0002</td> <td>No I/O processing during the booting test</td> </tr> <tr> <td>0x0004</td> <td>Manufacturer interface operating</td> </tr> <tr> <td>0x0010</td> <td>No I/O processing: invalid configuration</td> </tr> <tr> <td>0x0020</td> <td>No I/O processing: fault rate exceeded</td> </tr> <tr> <td>0x0040/ 0x0080</td> <td>No I/O processing: configured module not plugged in</td> </tr> </tbody> </table>	Coding	Description	0x0000	I/O processing, if required with errors, see other error codes	0x0001	No I/O processing (CPU not in RUN)	0x0002	No I/O processing during the booting test	0x0004	Manufacturer interface operating	0x0010	No I/O processing: invalid configuration	0x0020	No I/O processing: fault rate exceeded	0x0040/ 0x0080	No I/O processing: configured module not plugged in
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Table 33: ELOP II Factory - System Signals for the Pulsed Outputs

## 5 Operation

The controller F20 is ready for operation. No specific monitoring is required for the controller.

### 5.1 Handling

Handling of the controller during operation is not required.

### 5.2 Diagnosis

A first diagnosis results from evaluating the LEDs, see Chapter 3.4.1.

The device diagnostic history can also be read using the programming tool.

## 6 Maintenance

No maintenance measures are required during normal operation.

If a failure occurs, the defective module or device must be replaced with a module or device of the same type or with a replacement model approved by HIMA.

Only the manufacturer is authorized to repair the device/module.

### 6.1 Faults

Refer to Chapter 3.1.1.1, for more information on the fault reaction of digital inputs.

Refer to Chapter 3.1.2.1, for more information on the fault reaction of digital outputs.

If the test harnesses detect safety-critical faults, the module enters the STOP\_INVALID state and will remain in this state. This means that the input signals are no longer processed by the device and the outputs switch to the de-energized, safe state. The evaluation of diagnostics provides information on the fault cause.

### 6.2 Maintenance Measures

The following measures are required for the device:

- Loading the operating system, if a new version is required
- Executing the proof test

#### 6.2.1 Loading the Operating System

HIMA is continuously improving the operating system of the devices. HIMA recommends to use system downtimes to load a current version of the operating system into the devices.

Refer to the release list to check the consequences of the new operation system version on the system!

The operating system is loaded using the programming tool.

Prior to loading the operating system, the device must be in STOP (displayed in the programming tool). Otherwise, stop the device.

For more information, refer to the programming tool documentation.

#### 6.2.2 Proof Test

HIMatrix devices and modules must be subjected to a proof test in intervals of 10 years. For more information, refer to the safety manual (HI 800 023 E).

## 7 Decommissioning

Remove the supply voltage to decommission the device. Afterwards pull out the pluggable screw terminal connector blocks for inputs and outputs and the Ethernet cables.

## 8 Transport

To avoid mechanical damage, HIMatrix components must be transported in packaging.

Always store HIMatrix components in their original product packaging. This packaging also provides protection against electrostatic discharge. Note that the product packaging alone is not suitable for transport.

## 9 Disposal

Industrial customers are responsible for correctly disposing of decommissioned HIMatrix hardware. Upon request, a disposal agreement can be arranged with HIMA.

All materials must be disposed of in an ecologically sound manner.





## Appendix

### Glossary

Term	Description
ARP	Address resolution protocol: Network protocol for assigning the network addresses to hardware addresses
AI	Analog input
AO	Analog output
COM	Communication module
CRC	Cyclic redundancy check
DI	Digital input
DO	Digital output
ELOP II Factory	Programming tool for HIMatrix systems
EMC	Electromagnetic compatibility
EN	European norm
ESD	Electrostatic discharge
FB	Fieldbus
FBD	Function block diagrams
FTT	Fault tolerance time
ICMP	Internet control message protocol: Network protocol for status or error messages
IEC	International electrotechnical commission
MAC address	Media access control address: Hardware address of one network connection
PADT	Programming and debugging tool (in accordance with IEC 61131-3), PC with SILworX or ELOP II Factory
PE	Protective earth
PELV	Protective extra low voltage
PES	Programmable electronic system
R	Read: The system variable or signal provides value, e.g., to the user program
Rack ID	Base plate identification (number)
Interference-free	Supposing that two input circuits are connected to the same source (e.g., a transmitter). An input circuit is termed <i>interference-free</i> if it does not distort the signals of the other input circuit.
R/W	Read/Write (column title for system variable/signal type)
SELV	Safety extra low voltage
SFF	Safe failure fraction, portion of faults that can be safely controlled
SIL	Safety integrity level (in accordance with IEC 61508)
SILworX	Programming tool for HIMatrix systems
SNTP	Simple network time protocol (RFC 1769)
SRS	System.rack.slot addressing of a module
SW	Software
TMO	Timeout
W	Write: System variable/signal is provided with value, e.g., from the user program
r <sub>PP</sub>	Peak-to-peak value of a total AC component
Watchdog (WD)	Time monitoring for modules or programs. If the watchdog time is exceeded, the module or program enters the ERROR STOP state.
WDT	Watchdog time

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